

# Evaluation of the Travelling Wave Dipole Antenna Parameters Using an Adaptive Neuro-Fuzzy System

Theodoros N. Kapetanakis, Ioannis O. Vardiambasis and G. S Liodakis



Telecommunications & Electromagnetic Applications Laboratory,  
Department of Electronic Engineering, Faculty of Applied Sciences,  
Technological Educational Institute (TEI) of Crete, Crete, Greece

**International Symposium on Ambient Intelligence and Embedded Systems (AmiEs-2016)**  
**22 - 24 September, 2016 Heraklion, Crete, Greece**

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## Abstract (1/2)

- This work presents an alternative method, based on artificial techniques, to manipulate the travelling wave dipole antenna radiation, using data extracted from their analytical solution.
- The Adaptive Network Fuzzy Inference System (ANFIS) has been used, as a basis for constructing a set of fuzzy rules with appropriate membership functions in order to obtain the theoretical data.

# Abstract (2/2)

## Basic references

- [1] T. N. Kapetanakis, I. O. Vardiambasis, G. S. Liodakis, and A. Maras “Solving the Inverse Loop Antenna Radiation Problem Using a Hybrid Neuro-Fuzzy System,” *20th Telecommunications Forum (TELFOR 2012)*, pp. 1193-1196, Belgrade, Serbia, 20-22 Nov 2012.
- [3] J.-S.R. Jang, “ANFIS: adaptive-network-based fuzzy inference systems”, *IEEE Trans Systems, Man Cybernetics*, vol. 23, no. 3, pp. 665-685, May 1993.
- [5] C.A. Balanis, *Antenna Theory, Analysis and Design*, 3rd ed., New York: Wiley, 2005

# ANFIS (1/5)

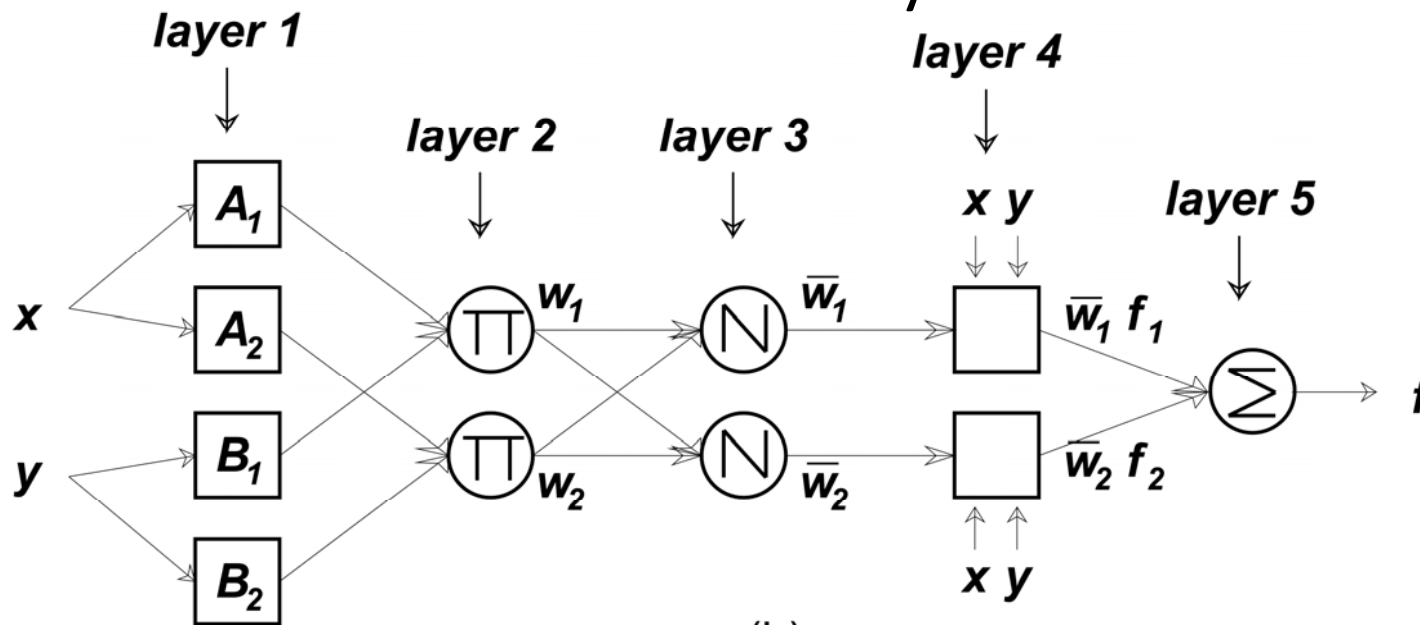
- The ANFIS, originally proposed in [3], has emerged as the combination of two powerful intelligent techniques: a) the artificial neural networks and b) the fuzzy logic approach, which have been adopted and tested to solve many real-world problems in recent years.
- This combination of fuzzy logic and neural networks into adaptive network architecture is the main fact making ANFIS so attractive in our investigation.

## ANFIS (2/5)

- Specifically, ANFIS integrates the greater learning capability of neural networks with a fuzzy logic approach to construct a fuzzy inference system, with membership function (MF) parameters, which are tuned using a back-propagation algorithm either alone or in combination with a least squares method.

# ANFIS (3/5)

- The architecture of the ANFIS network is shown above. It is structured in five layers.



Rule 1: If  $x$  is  $A_1$  and  $y$  is  $B_1$ , then  $f_1 = p_1x + q_1y + r_1$ ,

Rule 2: If  $x$  is  $A_2$  and  $y$  is  $B_2$ , then  $f_2 = p_2x + q_2y + r_2$

# ANFIS (4/5)

- **Layer 1:** Every node  $i$  in this layer is an adaptive node with a node function. Can be any appropriate parameterized membership function, such as the generalized bell function, the Gaussian function, or the sigmoid function.

$$O_{1,i} = \mu_{A_i}(x) \quad \text{for } i=1,2 \qquad O_{1,i} = \mu_{B_{i-2}}(y) \quad \text{for } i=3,4$$

- **Layer 2:** Every node in this layer is a fixed node labeled  $\Pi$ , whose output is the product of all the incoming signals representing the firing strength of a rule, or in other words performing the fuzzy AND function.

$$O_{1,i} = w_i = \mu_{A_i}(x) \cdot \mu_{B_i}(y) \quad i = 1,2$$



# ANFIS (5/5)

- **Layer 3:** Every node in this layer is a fixed node labeled N. The node i calculates the ratio of the i<sup>th</sup> rule's strength to the sum of all rules' firing strengths. The output of this layer is called normalized fire strength.

$$O_{3,i} = \bar{w}_i = \frac{w_i}{(w_1+w_2)} \quad i = 1,2$$

- **Layer 4:** Every node i in this layer is an adaptive node with node function:

$$O_{4,i} = \bar{w}_i f_i = \bar{w}_i (p_1 x + q_1 y + r_1)$$

where  $\bar{w}_i$  is a normalized strength from layer 3 and  $(p_i, q_i, r_i)$  is the parameter set of this node. Parameters in this layer are referred to as consequent parameters

- **Layer 5:** The single node in this layer is a fixed node, which computes the overall output as the summation of all incoming signals.

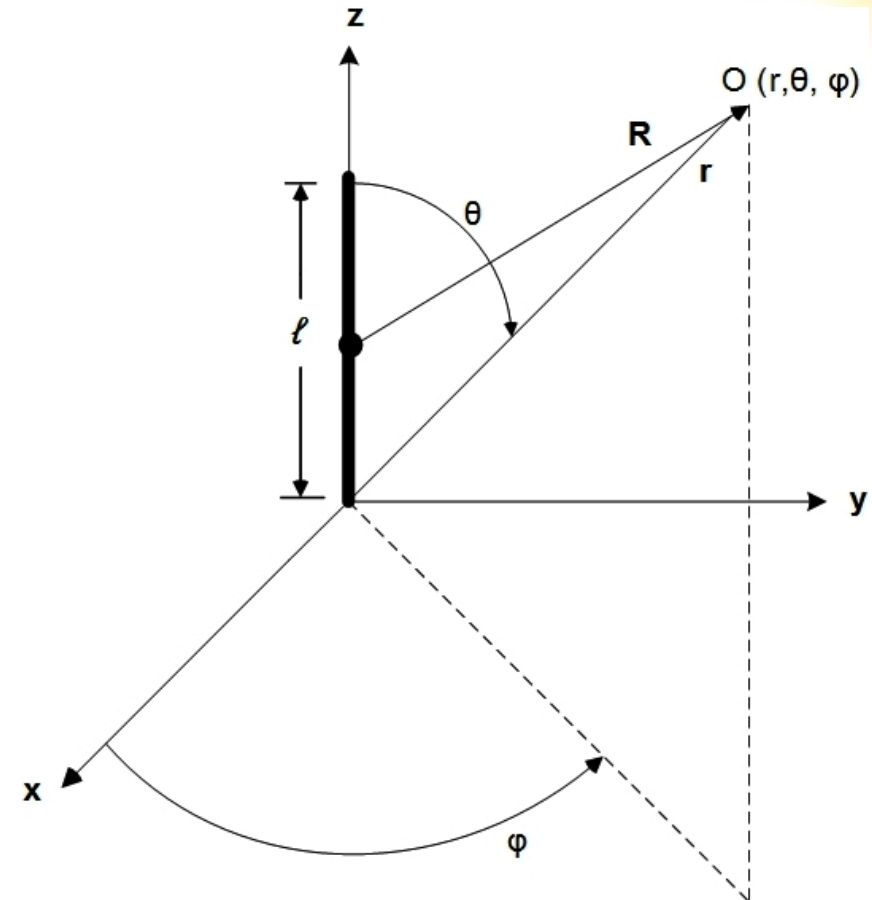
$$\text{Overall Output} = O_{5,i} = \sum_i \bar{w}_i f_i = \frac{\left( \sum_i w_i f_i \right)}{\sum_i w_i}$$

# Electromagnetic Problem Formulation (1/3)

- The problem consists of a long wire of length  $\ell$  directed along the z-axis.
- The current distribution is

$$\mathbf{I} = \hat{\mathbf{a}}_z I_0 e^{-jk_z z'}$$

where  $k_z$  the phase constant of the wave along the wire.



Travelling wave dipole geometry

## Electromagnetic Problem Formulation (2/3)

The radiation resistance can be obtained after some extensive mathematical manipulations from:

$$R_r = \frac{2P_{\text{rad}}}{|I_0|^2} = \frac{n}{2\pi} \left[ 1.415 + \ln\left(\frac{k\ell}{\pi}\right) - C_i(2k\ell) + \frac{\sin(2k\ell)}{2k\ell} \right]$$

Where  $P_{\text{rad}}$  the total radiated power,  $I_0$  the current amplitude,  $C_i(x)$  the cosine integral,  $n$  the intrinsic impedance,  $k$  the wave number and  $\ell$  the length of the antenna [4].

## Electromagnetic Problem Formulation (3/3)

The parameter which defines the directional properties of the antenna is the directivity and mathematically defined by the equations:

$$D(\theta) = \frac{4\pi U(\theta)}{P_{\text{rad}}} = \frac{2 \cdot \sin^2(kL \sin^2(\theta/2)) \cdot \cos^2(\theta/2)}{\cos^2(\theta/2) \cdot \left[ 1.415 + \ln\left(\frac{2l}{\lambda}\right) - \text{Ci}(2kl) + \frac{\sin(2kl)}{2kl} \right]}$$

$$C_i(x) = -\int_x^\infty \frac{\cos(\tau)}{\tau} d\tau = \int_\infty^x \frac{\cos(\tau)}{\tau} d\tau$$

Where  $P_{\text{rad}}$  the total radiated power,  $I_0$  the current amplitude,  $C_i(x)$  the cosine integral,  $k$  the wave number and  $l$  the length of the antenna [4]

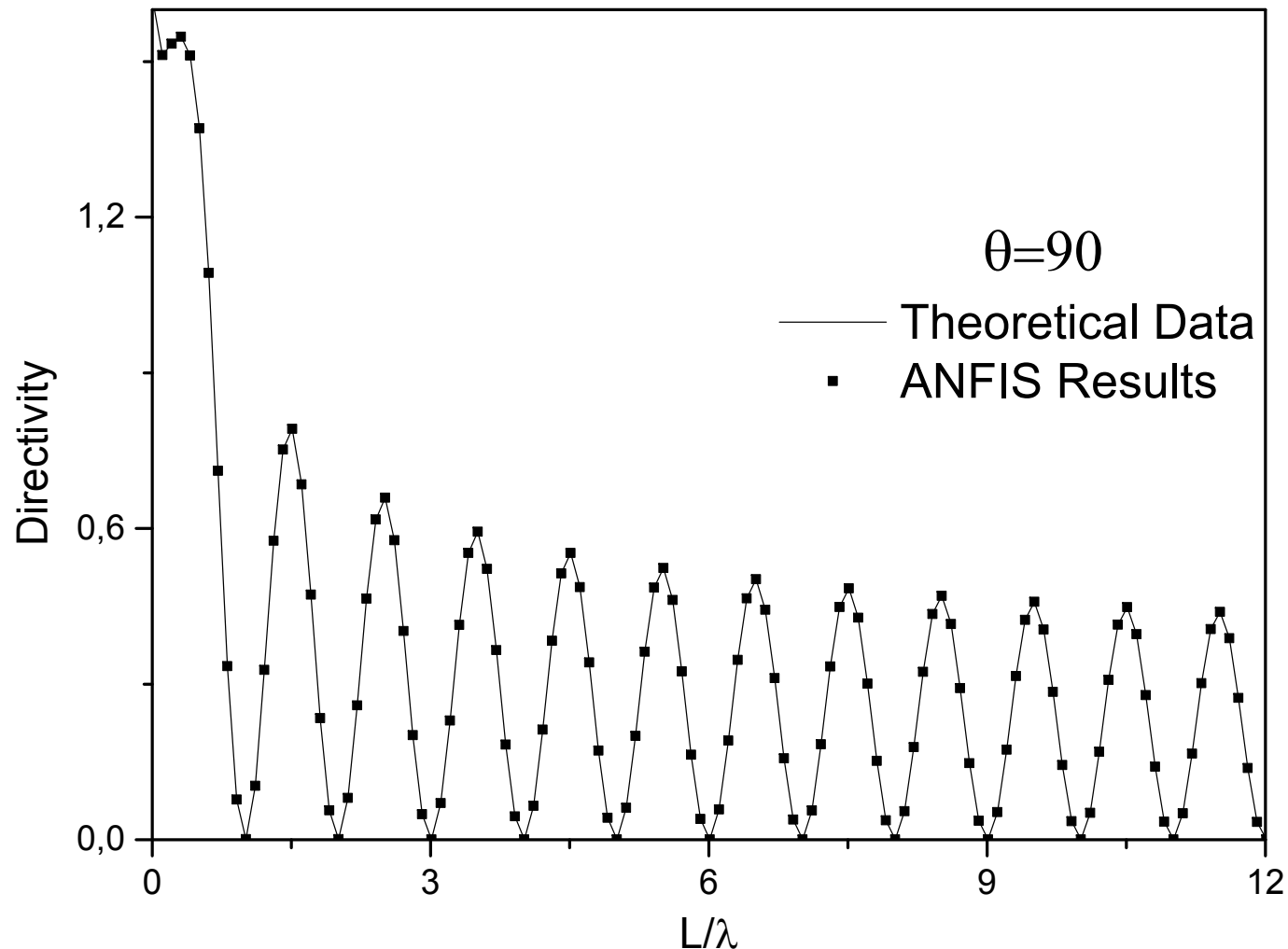
## ANFIS model (1/2)

- In this work, two neuro-fuzzy models are designed in order to estimate the travelling wave antenna radiation parameters.
- Using the first model, radiation resistance  $R_r$  is obtained as a function of antenna length  $\ell$  and current amplitude  $I_0$  (as input variables).
- The second model, the directivity  $D_0$  is obtained as a function of antenna length  $\ell$  and current amplitude  $I_0$  (as input variables).

## ANFIS model (2/2)

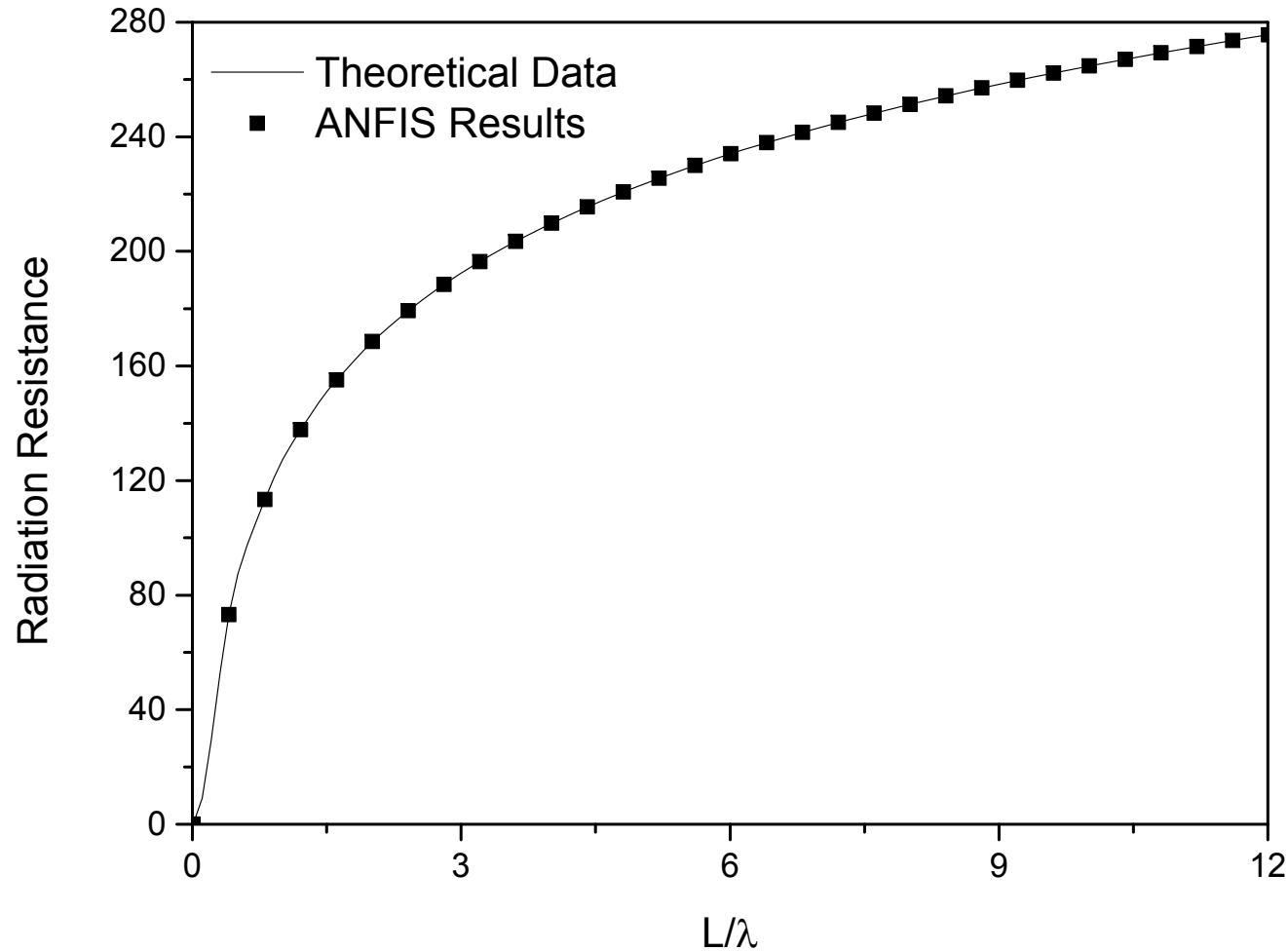
- In our model, 600 analytically extracted datasets were used as training (500) and testing (100) data for both models.
- The MFs' types tested include the Gaussian, the sigmoidally, the generalized bell, the Gaussian combination, the s-shaped, the Z-shaped, and the  $\Pi$ -shaped.
- Finally, 5 Gaussian and 8 Gaussian combination MFs were used for the models, respectively.

# Numerical results (1/4)



Comparison of directivity  $D_0$  (dimensionless) for a travelling wave dipole for various lengths.

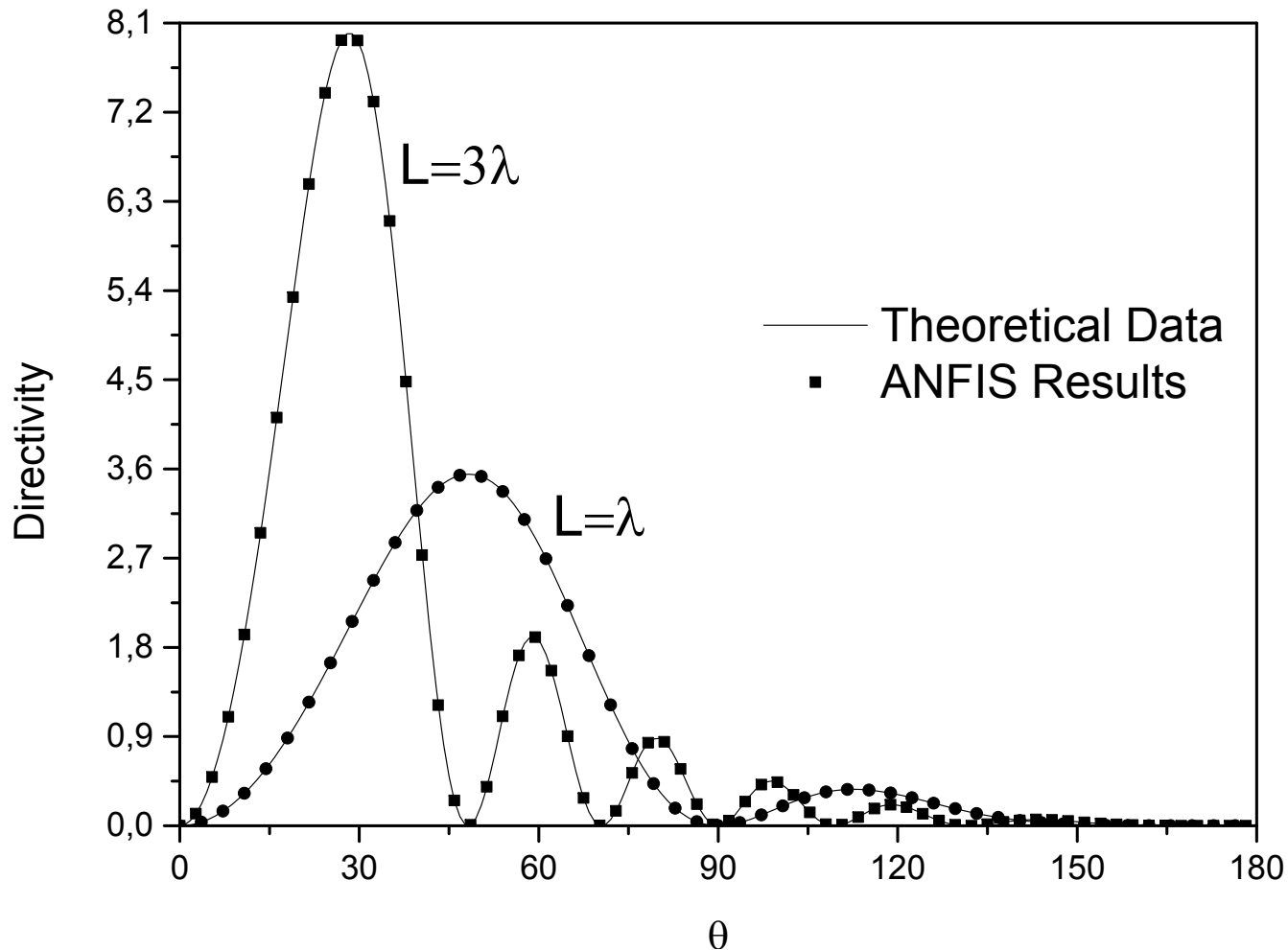
# Numerical results (2/4)



Comparison of radiation resistance  $R_r$  for a finite dipole for various lengths.

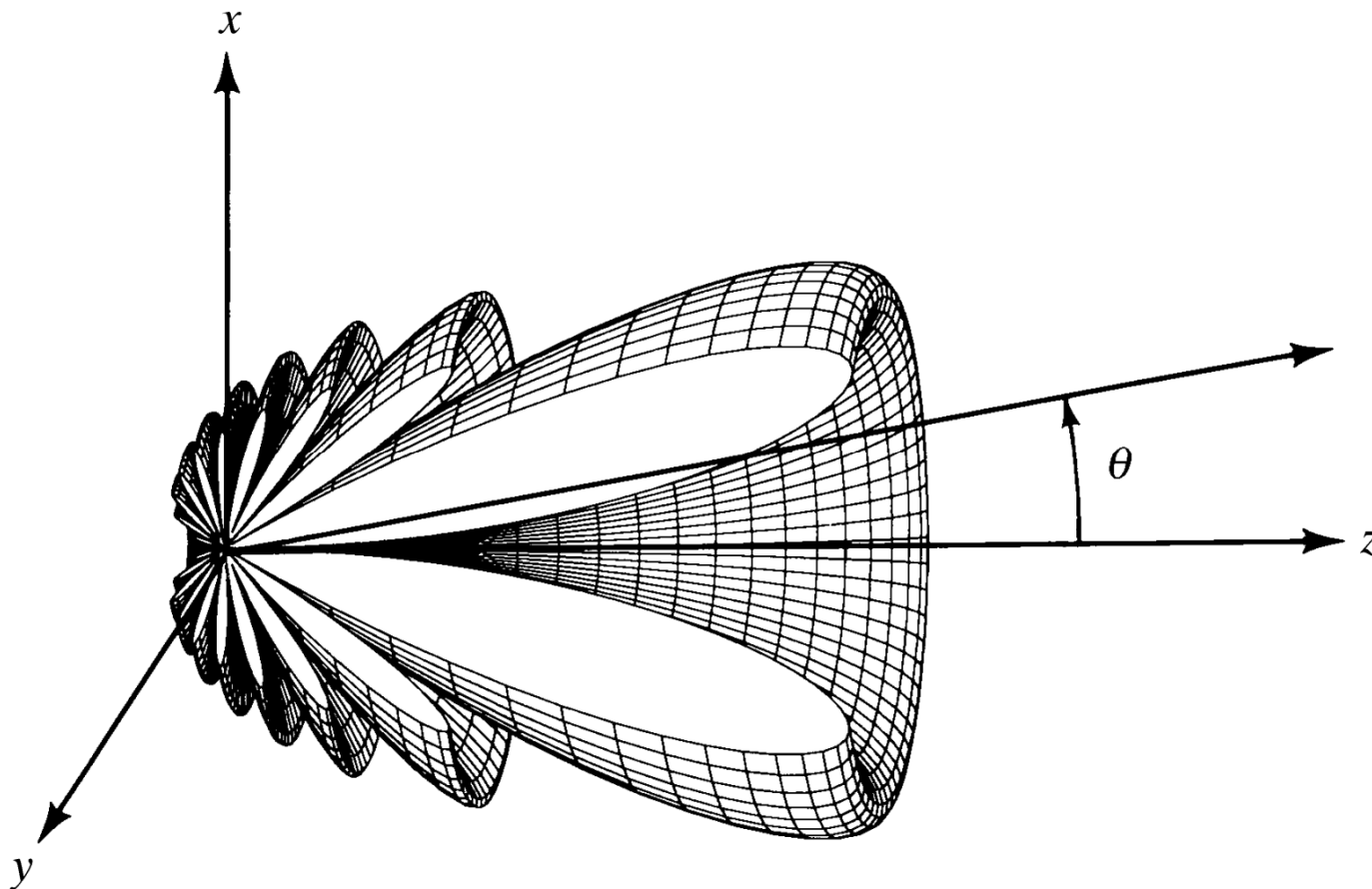


# Numerical results (3/4)



Comparison of directivity  $D_0$   $L=3\lambda$  and  $L=\lambda$  for various  $\theta$ .

# Numerical results (4/4)



3D pattern of a travelling wave dipole of  $\ell=5\lambda$

[C.A. Balanis, *Antenna Theory, Analysis and Design*, 3rd ed., New York: Wiley, 2005]

# Conclusion

- In this paper, a neuro fuzzy based generic algorithm are proposed to analyze the radiation parameters of a travelling dipole.
- The results obtained using the proposed algorithm were found matching with those obtained using the analytical solution.
- From the results, it is evident that the proposed algorithm is convenient to implement antenna radiation parameters estimation.

# References

- [1] T. N. Kapetanakis, I. O. Vardiambasis, G. S. Liodakis, and A. Maras “Solving the Inverse Loop Antenna Radiation Problem Using a Hybrid Neuro-Fuzzy System,” *20th Telecommunications Forum (TELFOR 2012)*, pp. 1193-1196, Belgrade, Serbia, 20-22 Nov 2012.
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- [4] D. Pujara, A. Modi, N. Pisharody, and J. Mehta, “Predicting the Performance of Pyramidal and Corrugated Horn Antennas Using ANFIS”, *IEEE Antennas and Wireless Propag. Letters*, vol. 13, pp. 293–296, 2014
- [5] C.A. Balanis, *Antenna Theory, Analysis and Design*, 3rd ed., New York: Wiley, 2005



**KEEP CALM AND  
THANK YOU FOR**

**YOUR ATTENTION**

**ANY QUESTIONS ?**

**NO? GREAT! BYE**



# **Estimation of Linear Wire Antenna Parameters Using Neural Networks**

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